EM-115 DC-MOTOR CONTROL UNIT 12-36V 25A 4-QUAD.



FEATURES:

- Small size
- Four quadrant drive
- High efficiency >92%
- Motor range 50-500W
- Rail mounting base fittable
- Adjustable current limit
- Adjustable ramp

EM-115 motor control unit is designed for big permanent magnet DC-motors. The power control is done with PWM method (Pulse Width Modulation). This facilitates high efficiency and small temperature losses. Thanks to a high switching frequency the unit operates quietly. A battery or a filtered DC-supply will do as a power source.

The maximum output given by the unit depends on the installation. When operating at maximum power output sufficient air ventilation has to be taken care of. The unit operates in 4-quadrants so it drives and brakes in both directions. The braking is done with regenerative way feeding braking energy back to power supply. When a battery is not used as a power source the braking energy will be fed to the internal resistance of the motor. The motor rpm can be set either with potentiometer, trim or external voltage signal. The output acceleration ramp and current limit are set with trims, the current limit is indicated with a red LED. A load affecting the motor rpm can be eliminated with a compensation trim. The power stage is protected against voltage peaks, overload and temporary shortcuts. Even the incorrect polarity does not damage the unit as long as a fuse of recommended value is used.

TECHNICAL DATA:

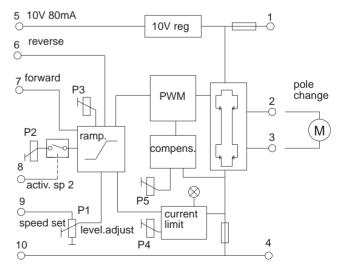
Supply voltage Idle current Recommended fuse Control potentiometer Load capacity

Motor voltage Control voltage range Voltage loss /V Current limit Operating frequency Ramp time On / Off control

Input impedance

Efficiency
Operating temp.
Dimensions
Weight

12...36 Vdc < 50mA 5-30A 1k..50k 25A RMS 50A mom. (5s) 0-30Vfrom 0-5V to 0-10V <1V when Im=25A 4..50A approx. 21kHz 0.3..10s >4V "on" <1V "off" pins 6.7 and 8 = 10kohm pin 9 = 100kohm >92% -10..50 °C 107*107*45 mm approx. 270 g



EM-115 OPERATING AND CONNECTING INSTRUCTIONS

IMPORTANT!

Check polarity before connecting! Use filtered 12-36VDC (ripple <20%) as operating voltage.

When motor current constantly exceeds 20A, proper air ventilation must be taken care of. Ambient temperature should not be over 50°C.

CONTROLS

P1-maximum level. Use to set maximum level. This is also the speed set for speed-1 in 2-step speed mode.

P2-speed-2 When using 2-step speed mode use P2 to set speed-2.

P3-acceleration / braking ramp Use ramp adj. to obtain smooth starting and running. The right value can be found just by testing the set.

P4-current limit

The operation of the current limit is indicated by a red LED next to the trim. Use it to set the desired maximum current to the motor, in other words max. torque.

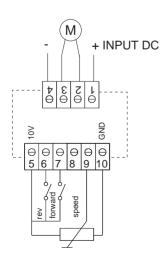
P5-compensation

Use this trim to compensate the load affecting the motor rpm. Set the motor rpm to approx. 50%, adjust ccw until the motor starts to twitch, then adjust carefully backwards till the twitching ends.

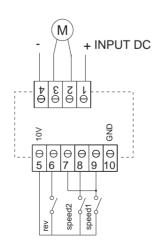
FUSE

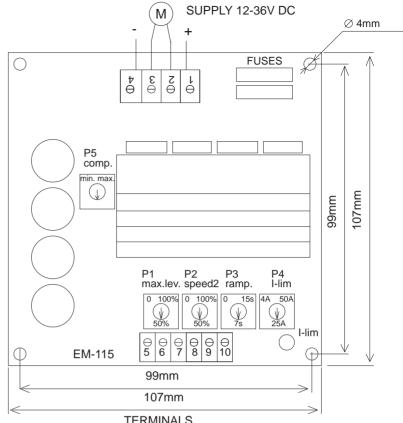
The fuse type is ATO 5-30A, according to the application.

Continuous rpm control, set with pot.meter, adjust range with P1. Switch to forward. Switch to change direction.



2-step speed mode (run / positioning) P1-speed1, P2-speed2 Activation with speed1 & speed2.

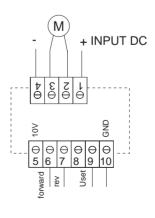




TERMINALS

- 1. Supply voltage 12-36V
- 2. Motor out +
- 3. Motor out -
- 4. Supply voltage 0V gnd
- 5. Control voltage approx. 10V 80mA
- 6. Reverse (master)
- 7. Forward
- 8. Speed-2 activation
- 9. Control input (U / pot.)
- 10. Signal 0V gnd

Continuous rpm control, set with voltage, adjust range with trim P1. Reverse and forward with TTL, CMOS or 0-24V signal.



Forward, OFF 0-1V, ON 4-30V Reverse, OFF 0-1V, ON 4-30V Speed (Uset) 0-5V to 0-10V = 0-100%