

Read status command. 20 bytes starting from address 41101.

| Byte array index | Term | Remark | Type |
|------------------|--------------------------|---|------|
| 0 | Bus mode | 0=Bus not controlling direction, 1=Bus controls direction, 2=Bus control with timeout, stop at timeout, 3=Bus control with local buttons stop, 4=Both 2 and 3 in use. Returns 0 in bus mode 2 when timeout and in bus mode 3 when local stop and with both in mode 4. | U8 |
| 1 | Direction | 0=off, 1=Forward, 2=Stop, 3=Backward | U8 |
| 2 | Motor A current: | Measured motor current. | U8 |
| 3 | Motor B current: | Measured motor current. | U8 |
| 4 | Current limit | Motor current limit value. | U8 |
| 5 | Set position | msb part of the 16bit value. | |
| 6 | Set position | Scaled servo set position value, 16bit, range 0-1023, lsb | U16 |
| 7 | Motor position | msb part of the 16bit value. | |
| 8 | Motor position | Scaled servo motor feedb ack position value, 16bit, range 0-1023, lsb | U16 |
| 9 | Motor A position counter | msb part of the 16bit value. | |
| 10 | Motor A position counter | 16bit motor position pulse counter value lsb part. | U16 |
| 11 | Motor B position counter | msb part of the 16bit value. | |
| 12 | Motor B position counter | 16bit motor position pulse counter value lsb part. | U16 |
| 13 | Supply voltage | Measured supply voltage value. | U8 |
| 14 | Motor A pwm value | Motor output pwm value 0-255 | U8 |
| 15 | Motor B pwm value | Motor output pwm value 0-255 | U8 |
| 16 | Fault code | 1=Homing, or position lost, 2=over current, 3=No pulses detected, 4=Position dif. too high, 5=Over voltage. 6=Safety edge activated, 7=Bus timeout with bus mode 2 and 4. | U8 |
| 17 | Inputs | Learn, disable, home and emergency inputs status on/off shown as bitmap: bit0=not in use,learn=bit1,disable=bit2, home=bit3, emergency=bit4. Example: bitmap 0b 00001010 means learn and home inputs are on, others are off. | U8 |
| 18 | Position set input | Analog value of position set input. | U8 |
| 19 | Safety edge input | Analog value of safety edge input. | U8 |

| Byte array index | Term | Remark | Type |
|------------------|------------------|--|------|
| 0 | Bus mode | 0=Bus not controlling position, 1=Bus controls position, 2=Bus control with timeout, stop at 5s timeout, 3=Bus control with local buttons stop, 4=Both 2 and 3 in use. Returns to 0 in bus mode 2 when timeout and in bus mode 3 when local stop and with both in mode 4. To continue, reset this by first setting bus mode to 0 and then again to wanted value. When timeout occurs, on board led shows timeout fail 7 blinks, motors are stopped. This can be reset locally by pressing shortly home/reset button. Or by bus with first setting bus mode to 0 and then to some value. | U8 |
| 1 | Position command | msb part of the 16bit value. | |
| 2 | Position command | 16b it position command for servo. Range 0-1023, lsb. | U16 |
| 3 | Command | 0=off, 4=home, 5=learn, 6=disable | U8 |
| 4 | Speed | Maximum speed value 0-255. | U8 |
| 5 | Current limit | Current limit value | U8 |

Parameters read/write Starting address 40101

| Byte array index | Term | Remark | Type |
|------------------|-------------|---|------|
| 0 | Parameter 1 | msb part of the 16bit value. | |
| 1 | Parameter 1 | Parameter 1 | U16 |
| 2 | Parameter 2 | msb part of the 16bit value. | |
| 3 | Parameter 2 | Parameter 2 | U16 |
| 4 | .. | | |
| 5 | .. | | |
| 6 | Parameter N | msb part of the 16bit value. | |
| 7 | Parameter N | Up to 44 parameters. Number of parameters can be read with device info. | U16 |

There can be 8bit and 16bit parameters in a device, but all parameters are transferred as 16bit. With 8bit parameters msb is ignored.

Writing parameters also saves them to non-volatile memory which can take about 50ms – 150ms.

Response message is sent when saving is done.

Please note parameter memory can last only 100 000 saving times,

when parameters like speed and current limit needs to be adjusted on the fly use control command instead.

Device info.

20 bytes starting from address 40001.

| Byte array index | Term | Remark | Type |
|------------------|------------------------|--|------|
| 0 | Protocol version | Value = 2 | U8 |
| 1 | Protocol minor version | Default = 0 Minor version can be used to distinct different control and status message configurations. | U8 |
| 2 | Not in use | | U8 |
| 3 | Device version | Version of the connected device. 10 means v1.0 in datasheet, 25 is v2.5 and so on. | U8 |
| 4 | Not in use | | U8 |
| 5 | Parameters | Number of parameters in a device, see datasheet for parameter descriptions | U8 |
| 6 | No in use | | U8 |
| 7 | Name letters | Number of letters in a device name. 1-11. | U8 |
| 8 | Char 1 | Name characters ASCII. Unused characters have value 0. | U8 |
| 9 | Char 2 | | U8 |
| 10 | Char 3 | | U8 |
| 11 | Char 4 | | U8 |
| 12 | Char 5 | | U8 |
| 13 | Char 6 | | U8 |
| 14 | Char 7 | | U8 |
| 15 | Char 8 | | U8 |
| 16 | Char 9 | | U8 |
| 17 | Char 10 | | U8 |
| 18 | Char 11 | | U8 |
| 19 | Not in use | | U8 |